

OPERATING INSTRUCTIONS

Two Wire Hall Effect Speed Sensor DSF xx15.xx xHV Series



Product ID

	Type #	Product #	Drawing #			
	DSF 1215.01 SHV S177 (6m)	304Z-05312	4-113.561 S177			
	DSF 1215.01 SHV S178 (3m)	304Z-05375	4-113.751			
	DSF 1415.01 AHV S90	304Z-03819	4-109.389 S90			
	DSF 1615.02 SHV (5m)	304Z-05259	4.113.354			
	DSF 1615.09 AHV	374Z-05722	115.039 Rev.6			
	DSF 1615.10 AHV	374Z-05870	115.039 Rev.6			
	DSF 2215.01 AHV S39	304Z-05408	4-107.307			
	DSF 2215.01 SHV (5m)	304Z-05214	4-113.120			
	DSF EH15.00 PHV	374Z-05725	115.046 Rev.1			
	DSF EH15.01 S1HV	3742608036	119682 Rev.000			
	DSF EH15.09 A1HV	374Z-05723	115.039 Rev.6			
	DSF EH15.09 A2HV	374Z-05724	115.039 Rev.6			
	DSF EH15.10 A1HV	374Z-05871	115.039 Rev.6			
	DSF EH15.10 A2HV	374Z-05872	115.039 Rev.6			
General						
Function	The speed sensors DSF xx15.xx	xHV are suitable, in c	conjunction with a pole			
	wheel, for generating square way	e signals proportiona	to rotary speeds. They			
	have a static behaviour, so that p	have a static behaviour, so that pulse generation is guaranteed down to a speed				
	corresponding to a frequency of 0 Hz. The sensing element is a magnetically					
	biased Hall effect semiconductor	biased Hall effect semiconductor, followed by a 2 wire amplifier.				
Technical data						
Supply voltage	9 VDC to 18 VDC, protected agai	9 VDC to 18 VDC, protected against reverse polarity				
Current consumption	Max. 10 mA (without load)					
Signal output	The sensor changes its resistance in the presence of ferrous metal. Typically, the					
	supply is provided via an 820 Oh	m resistor. The currer	nt impulses generated are			
	analysed on this resistor. Pulse le	evels of 2.2 V peak-pe	eak are generated across			
	the 820 Ohm resistor, with a d.c.	component of 34 supp	oly voltage (see			
	connection diagram).					
Start up behavior	The sensor will change its output	after the passing of t	he second tooth.			
Frequency range	0 Hz 15 kHz		-			
Electromagnetic	According to Directive 2004/108/EC, EN 61000-6-2 and 61000-6-4:					
compatibility (EMC):	Electrostatic discharge into housing, cable shield and wires: up to ± 4 kV peak					
	according to IEC 61000-4-2, severity level 2					
	Radiated electromagnetic field: up to 30 V/m, 50% AM, 1 kHz in the range of					
	1 MHz to 1000 MHz according	1 MHz to 1000 MHz according to IEC 61000-4-3, severity level 3				
	Fast electrical transients/burst	s, coupled to sensor	cable with a capacitive			
	coupling clamp: up to ±4 kV pe	eak according to IEC	61000-4-4, severity level 4			
Housing	Stainless steel 1.4305, front side	sealed hermetically a	ind resistant against			
	splashing water, oil, conducting c	arbon- or terrous dus	t and salt mist. Electronic			
	components potted in chemical a	nd age proof syntheti	c resin.			
	Dimensions according to drawing					

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Sim, 11.02.2011	RM, 14.02.2011	APPROVED		117898	005
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OPERATING INSTRUCTIONS

Sensor type	Connection type	Jaquet part number
DSF 1215.01 SHV S177	Cable	824L-35053
DSF 1215.01 SHV S178	Cable	824L-35053
DSF 1415.01 AHV S90	Connector	820E-31142
DSF 1615.02 SHV (5m)	Cable	824L-35053
DSF 1615.09 AHV	Connector	385E-73612
DSF 1615.10 AHV	Connector	385E-73612
DSF 2215.01 AHV S39	Connector	820E-31142
DSF 2215.01 SHV (5m)	Cable	824L-35053
	Cable with integrated	824L-36622 (cable)
DSF EH15.00 PHV	connector	CIR06 (connector)
DSF EH15.01 S1HV	Cable	824L-35053
DSF EH15.09 A1HV	Connector	385E-73612
DSF EH15.09 A2HV	Connector	385E-73612
DSF EH15.10 A1HV	Connector	385E-73612
DSF EH15.10 A2HV	Connector	385E-73612

Cable		
	Jaquet cable type	Properties
		FEP Teflon cable, 4-wire (brown wire is not connected), 0.2 mm ² (AWG 24), outer-Ø max. 4.2 mm, bending radius min. 60 mm, screened (metal net), white
	824L-35053	Operating temperature: -100℃ to +150 ℃
		Armoured cable: 6-wire, 0.6 mm ² (AWG 20), PEIC insulated, fire retardant, low smoke, PVC and halogen free, oil-proof, waterproof, outer- \emptyset max. 13.0 mm, min. bending radius = 30 mm (static) and 65 mm (dynamic), screened (metal net), black casing (silicone)
	824L-36622	Operating temperature: -40℃ to +150 ℃

Connector

Jaquet connector type	Manufacturer code
	Mates with MS3106A-10SL-4S
	Operating temperature: -55℃ to +125℃
385E-73612	Plug-and-socket connection: IP67
	MS3102A-10SL-3P/H 097
	Operating temperature: -55℃ to +125℃
820E-31142	Plug-and-socket connection: IP67
	ITT Cannon Veam CIR06AG-10SL-3P-F80-T12
CIR06	Operating temperature: -55℃ to +125℃

Requirements for pole wheel	Toothed wheel of a magnetically permeable material (e.g. Steel 1.0036)			
	Optimal performance with			
	Involute gear			
	Tooth width > 10 mm			
	Side offset < 0.2 mm			
	Eccentricity < 0.2 mm			
Air gap between sensor and	Air gap between pole wheel (involute gear) and sensor housing:			
pole wheel	Module 1: 0.20.5 mm			
	Module 2: 0.21.5 mm			
	Module 4 (and larger): 0.22.5 mm			
Insulation	Housing and electronics galvanically separated (500 V/50 Hz/ 1 min)			
Protection class	IP69 (head) and IP67 (connector, cable outlet)			
Vibration immunity	5 g in the range of 5 2000 Hz			
Shock immunity	50 g for 20 ms, half sine wave			
Temperature	Operating temperature of entire sensor: -40° +125℃			

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Sim, 11.02.2011	RM, 14.02.2011	APPROVED		117898	005
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OPERATING INSTRUCTIONS

Further Information	
Safety	All mechanical installations must be carried out by an expert. General safety requirements have to be met.
Connection	 The sensors must be connected according to the sensor drawing. Sensor wires are susceptible to radiated noise. Therefore, the following points have to be considered when connecting a sensor: The sensor wires must be positioned as far as possible from large electrical machines. They must not run in the vicinity of power cables. It is advantageous to keep the distance between sensor and instrument as short as possible. If the signal requirements are met, the sensor cable may be lengthened via a terminal box located in an IP20 connection area in accordance with EN 60529.
Installation	The sensor has to be aligned to the pole wheel according to the sensor drawing. A deviation in positioning may affect the performance and decrease the noise immunity of the sensor. Within the air gap specified the amplitude of the output signals is not influenced by the air gap. The smallest possible pole wheel to sensor gap should be set, however, the gap should be set to prevent the face of the sensor from touching the pole wheel. The sensor should be positioned such that the center of the sensor face corresponds to the middle of a pole wheel tooth. For larger teeth a misalignment of the sensor center to the middle of a tooth is permissible, however, the center of the sensor must be at a minimum of 3 mm from either edge of the pole wheel under all operating conditions. A solid and vibration free mounting of the sensor is important. Sensor vibration relative to the pole wheel may add extranious and/or spurious noise to the signal. The sensors are insensitive to oil, grease etc. and can be installed in arduous conditions.
Maintenance	Product cannot be repaired.
Transport	Product must be handled with care to prevent damage of the front face.
Storage	Product must be stored in dry conditions. The storage temperature corresponds to the operation temperature.
Disposal	Product must be disposed of properly, it must not be disposed as domestic waste.

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Sim, 11.02.2011	RM, 14.02.2011	APPROVED		117898	005
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